# Specification & Complexity of Replicated Objects

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# This talk

Theoretical exploration of highly-available replicated data stores

- Framework for reasoning
- Results on:
  - Achievable consistency
  - Lower bounds on message size and metadata overhead
- Clarify the landscape

# Replicated data stores

Geo-distributed systems driving Google, Facebook, Amazon, etc.

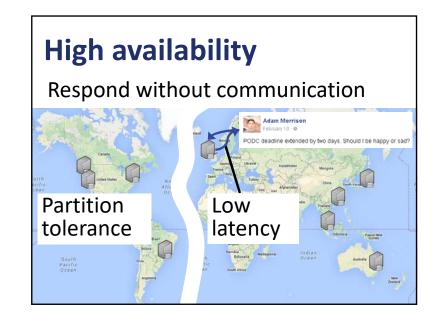


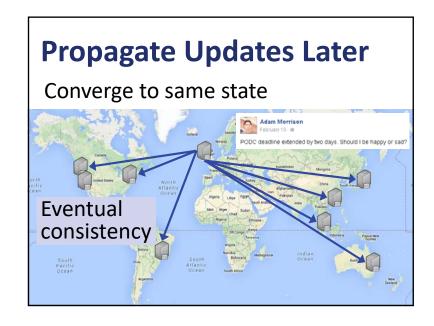
#### This talk

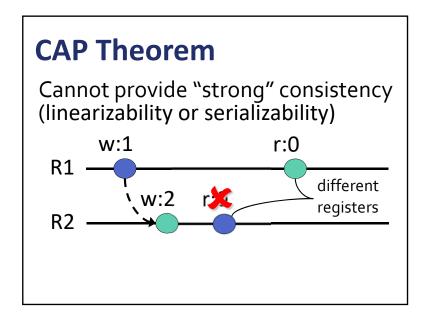
Theoretical exploration of highly-available replicated data stores

Asynchronous message-passing algorithms implementing shared objects

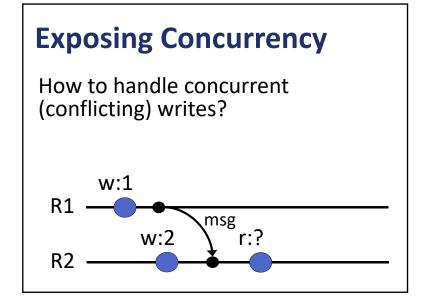


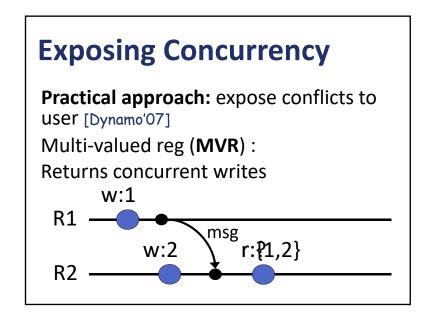


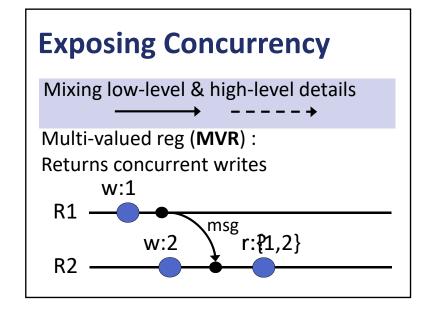


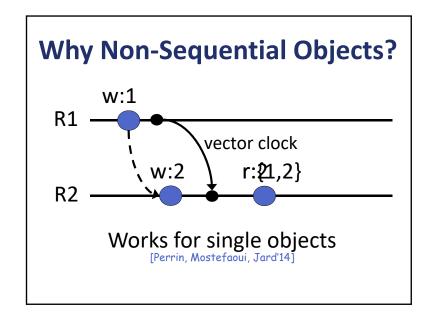


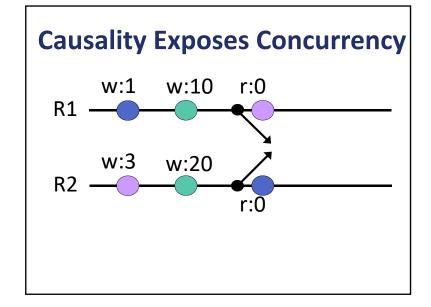
# Causal Consistency [Ahamad, Neiger, Burns, Kohli, Hutto] If an operation is visible, so are its dependencies: w:1 R1 r:1 w:3 R2 r:3 r:3 R3

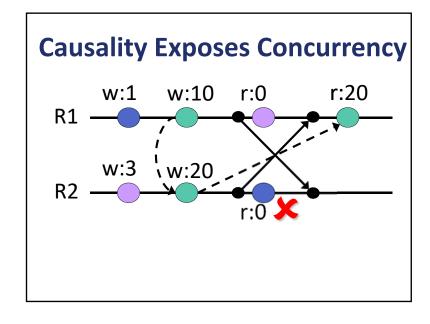








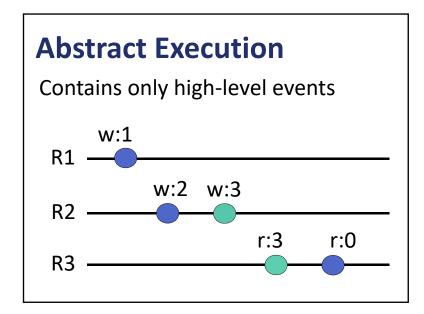


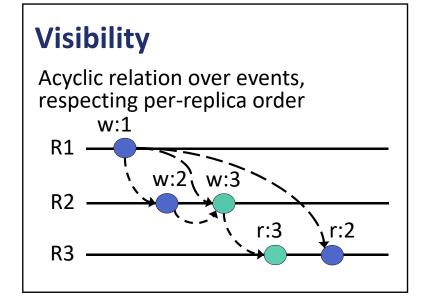


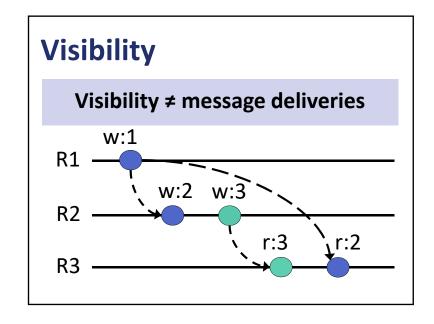
### **Avoiding Low-Level Details**

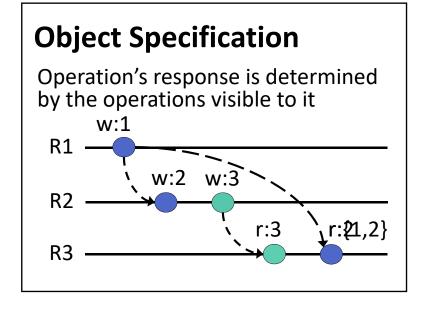
Specify replicated objects using visibility in abstract executions

[Burckhardt, Gotsman, Yang, Zawirski]





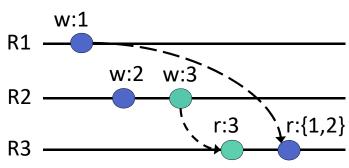




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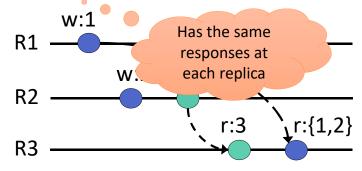
# **Object Specification**

Concrete execution **implements** the object if it **complies** with an abstract object execution



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Concrete execution **implements** the object if it **complies** with an abstract object execution



# **Eventual consistency**

Building reliable distributed systems
staw > Eventual consistency. This is a special system of the s

# **Eventual consistency**

[Burckhardt, Gotsman, Yang, Zawirski]

Infinite abstract execution is **eventually consistent** if an operation is invisible to only finitely many operations

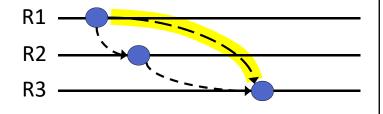
Implies Vogels' informal definition

### **Causal consistency**

**Consistency model:** prefix-closed set of

abstract executions

Causal consistency: visibility is transitive



#### **Comparing Consistency Models**

A consistency model is **satisfied** when all concrete executions comply with one of its abstract executions

Fewer abstract executions

⇒ stronger model

causal

Bayou, PRACTI, COPS... satisfy causal consistency

serializability

Can we satisfy a stronger model?

# **Consistency Limit Result**

<u>Theorem:</u> Eventually consistent data store D does not satisfy a consistency model stronger than observable causal consistency (OCC)

OCC hides concurrency unless

user can infer it

causal consistency
α • OCC

# Deriving OCC Goal: Comply with abstract execution without concurrency w:1 R1 w:2 R2 R3

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Deriving OCC
<b>Goal:</b> Comply with abstract execution without concurrency.
w:3 w:1
R2
R3 r:2
R4 ************************************

	Our Theorem	CAC Theorem [Mahajan, Alvisi, Dahlin]
Liveness	Eventual consistency	One-way convergence (stronger)
Strongest consistency	OCC	Causal consistency (weaker)
Tight?	Don't know	Yes*
Assumptions	invisible reads	
	msg sending	real time

# Message lower bound

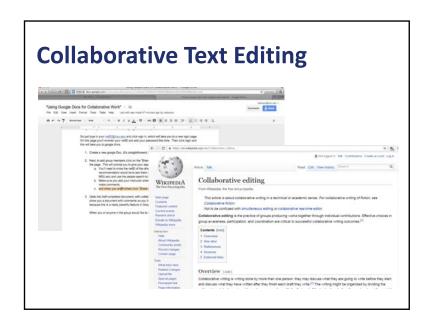
**n**: # of replicas

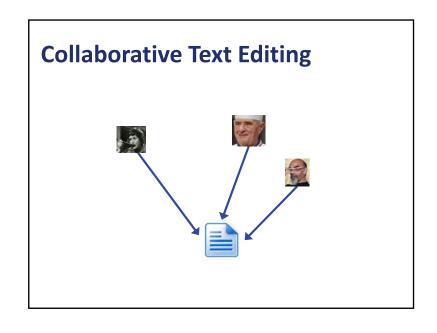
s: # of MVRs, each of ~lg k bits

<u>Theorem:</u>  $\Omega(\min\{n, s\} \lg k)$  bit message lower bound for causally & eventually consistent data store

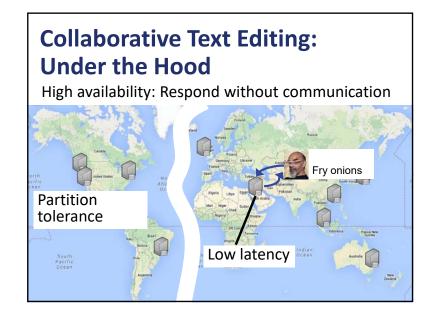
Basically: vector clock if  $s \ge n$ 

What if *s* << *n*?













ins(a, pos) del(a) read() (inserted elements are unique)

Every op returns state of the list:  $ins(x, 0) : x \quad ins(a, 1) : xa$ 





#### **List Semantics**

Shared document editing operations:

ins(a, pos) del(a) read() (inserted elements are unique)

Every op returns state of the list

#### **List Semantics**

What does previous mean?

Can't use messages received (low-level)
Again, use visibility in abstract executions

Every op returns state of the list
List of elements, each with previous ins()
but no previous del()

#### **List Semantics**

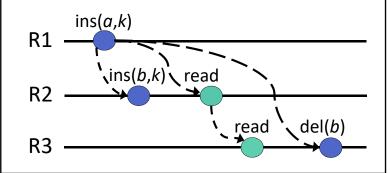
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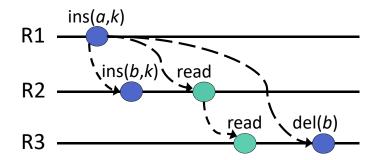
#### **Implementing a List Object**

Every concrete execution complies with an abstract list execution



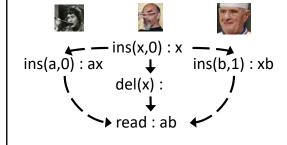
#### **Implementing a List Object**

Each operation returns **ordered** list of elements with visible ins() but no visible del()





Strong list order: ∃ irreflexive relation that's transitive & total on all inserted elements
Intuition: remembers deleted elements

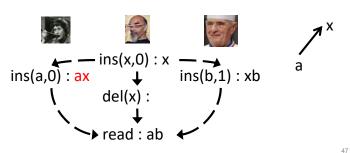


46

#### **Strong List Specification**

**Strong list order**: ∃ irreflexive relation that's transitive & total on **all inserted elements** 

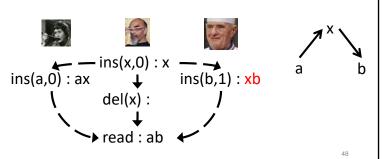
Intuition: remembers deleted elements



### **Strong List Specification**

**Strong list order**: ∃ irreflexive relation that's transitive & total on **all inserted elements** 

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#### **Strong List Specification**

**Strong list order**: ∃ irreflexive relation that's transitive & total on **all inserted elements Intuition:** remembers deleted elements







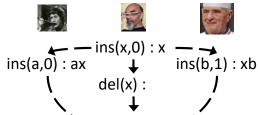


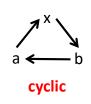
ins(a,0) : ax ins(b,1) : xbdel(x) : read : ab

49

#### **Strong List Specification**

Strong list order: ∃ irreflexive relation that's transitive & total on all inserted elements
Intuition: remembers deleted elements

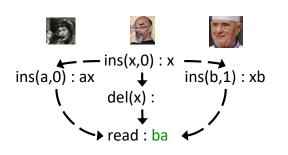


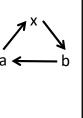


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#### **Weak List Specification**

Weak list order: ∃ irreflexive relation that's transitive & total on elements returned by an operation





Algorithm for the Strong List

Replicated Growable Array (RGA)

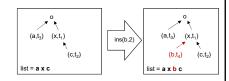
[Roh, Jeon, Kim, Lee. JPDC 2011]

Resolve order of elements concurrently inserted at the same position with Timestamped Insertion (TI) Data Structure

Keep tombstones for deleted elements

#### **RGA: Timestamped Insertion**

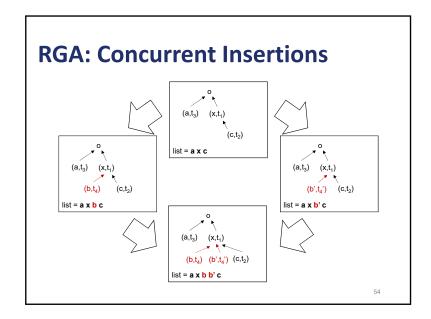
Stores list content & timestamp metadata



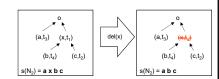
To **read**, list elements in **prefix** order, with children appearing in decreasing timestamp order

To **insert** at position *k*, pick a timestamp > than all existing timestamps; insert new node as the child of the immediately preceding element

Message: the new node



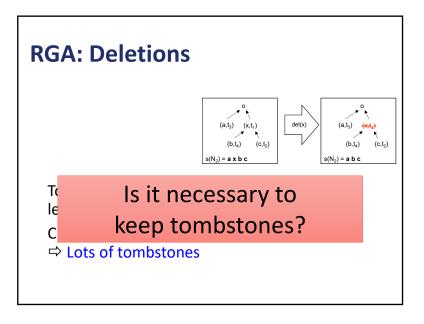
#### **RGA: Deletions**



To **delete** just mark the element as deleted, leaving a tombstone

Change = deletion + insertion 

⇒ Lots of tombstones



#### **Are Tombstones Necessary?**

Some algorithms don't have them:

• Treedoc [Preguiça, Marqués, Shapiro, Letia. ICDCS 2009] Logoot [Weiss, Urso, Molli. ICDCS 2009]

Element position = sequence of edge labels on the path from the root of the tree

Label stays the same after nodes are deleted

 Operational transformations (OT) Log updates; transform them locally

#### **Are Tombstones Necessary?**

Some algorithms don't have them:

Still a lot of metadata • Treedoc [Preguiça, Marqués, Shaping Logoot Weigh

sequence of edge labels on FI from the root of the tree the

Label stays the same after nodes are deleted

size of list state Metadata overhead =  $\frac{\text{size of observable list}}{\text{size of observable list}}$ 

#### **Metadata Lower Bound**

There is an execution with *D* deletions, in which a replica has  $\Omega(D)$ -bit metadata overhead

- ✓ Even with **causal** atomic broadcast
- ✓ Even for **weak** specification
- × Only for **push-based** protocols
  - -a replica sends updates to other replicas & merges updates from other replicas into its state as soon as possible

#### **Metadata Lower Bound**

There is an execution with *D* deletions, in which a replica has  $\Omega(D)$ -bit metadata overhead

Execution in which the list at some replica is "\*" but replica's state is  $\Omega(D)$  bits

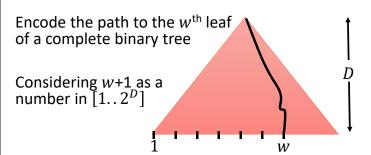
#### **Proof Technique**

There are  $2^D$  such strings  $\Rightarrow$  for some w, size of replica state after  $\alpha_w$  is  $\Omega(D)$  bits

 $\forall D$ -bit string w, construct an execution  $\alpha_w$  s.t.:

- ✓ A replica performs D deletions and receives no messages
- $\checkmark$  After  $\alpha_w$ , the list at the replica is "\*"
- $\checkmark$  w can be decoded from the state of the replica
- √ The replica has no pending messages

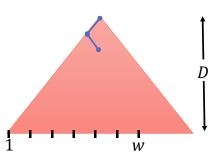
#### **Encoding** *w*



- ✓ After  $\alpha_w$ , the list at the replica is "\*"
- $\checkmark$  w can be decoded from the state of the replica

#### Example: encoding w = 01

 $\begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ send  $m_1$   $\begin{bmatrix} 1 \\ 1 \end{bmatrix}_1 \begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ send  $m_2$   $\begin{bmatrix} 1 \\ 1 \end{bmatrix}_1 \begin{bmatrix} 2 \\ 2 \end{bmatrix}_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ send  $m_3$   $\begin{bmatrix} 1 \\ 1 \end{bmatrix}_1 \begin{bmatrix} 2 \\ 2 \end{bmatrix}_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ send  $m_4$   $\begin{bmatrix} 1 \\ 1 \end{bmatrix}_2 \begin{bmatrix} 2 \\ 2 \end{bmatrix}_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ send  $m_4$  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}_2 \begin{bmatrix} 2 \\ 2 \end{bmatrix}_2 \begin{bmatrix} 0 \\ 0 \end{bmatrix}_0$ 

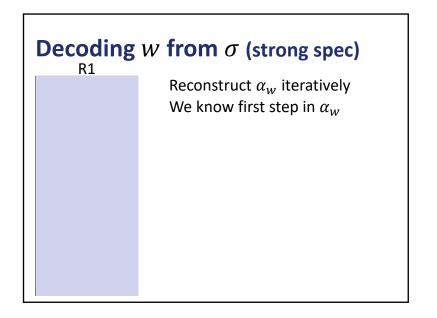


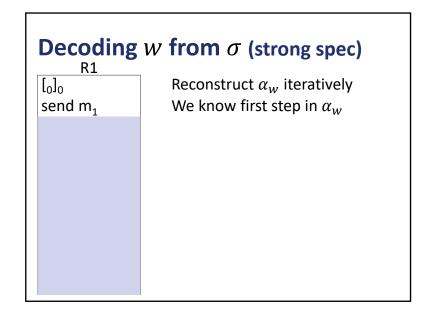
**Output:** encoding replica state,  $\sigma$ 

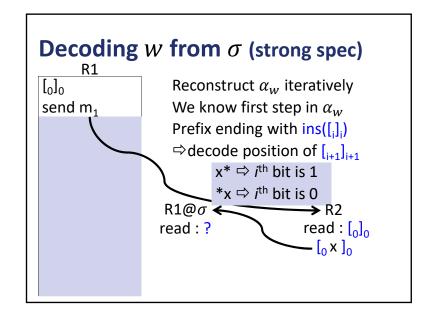
#### **Decoding** w from $\sigma$ (strong spec)

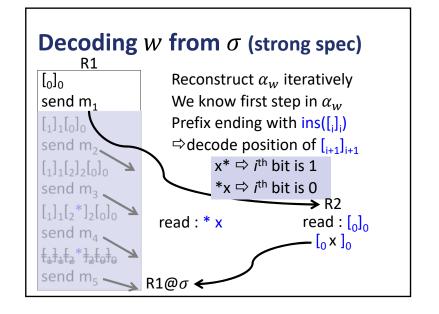
 $\begin{bmatrix} [_{0}]_{0} \\ \text{send } m_{1} \\ [_{1}]_{1}[_{0}]_{0} \\ \text{send } m_{2} \\ [_{1}]_{1}[_{2}]_{2}[_{0}]_{0} \\ \text{send } m_{3} \\ [_{1}]_{1}[_{2}*]_{2}[_{0}]_{0} \\ \text{send } m_{4} \\ \underbrace{\{_{1}\}_{1}[_{2}*\}_{2}[_{0}]_{0}}_{\text{send } m_{5}}$ 

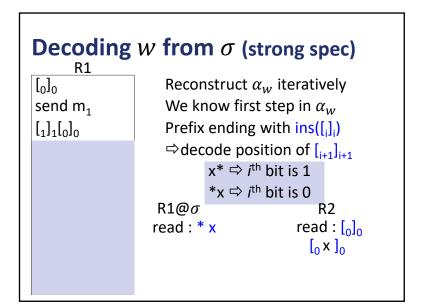
Reconstruct  $\alpha_w$  iteratively

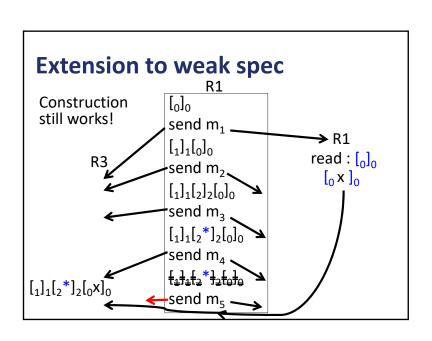












#### **Decoding** w from $\sigma$ (strong spec)

 $\begin{bmatrix} l_0 l_0 \\ \text{send } m_1 \\ [l_1]_1 [l_0]_0 \\ \text{send } m_2 \end{bmatrix}$ 

Reconstruct  $\alpha_w$  iteratively
We know first step in  $\alpha_w$ Prefix ending with  $\operatorname{ins}([_i]_i)$   $\Rightarrow$  decode position of  $[_{i+1}]_{i+1}$   $x^* \Rightarrow i^{\text{th}}$  bit is 1  $*x \Rightarrow i^{\text{th}}$  bit is 0
R1@ $\sigma$ R2
read: \*xread:  $[_0]_0$ 

#### **Extensions**

- Result holds for client-server model
  - Proof's execution satisfies atomic broadcast:
     All replicas receive messages in same order
  - Replicas can maintain server's state
  - Encoding replica receives no messages =
     Server is in its initial state
- $\Rightarrow \Omega(D)$ -bit metadata overhead for clients

#### **Weak Specification**

- Result holds also for the weak specification
- Comes from client-server model
- For P2P, equivalent to strong spec?
- Captures real systems?
   Conjecture: Jupiter (Google Docs algorithm)

#### **READ MORE ABOUT IT...**

 Hagit Attiya, Faith Ellen, Adam Morrison: Limitations of Highly-Available Eventually-Consistent Data Stores.

PODC 2015 & IEEE TPDS 2016

 Hagit Attiya, Sebastian Burckhardt, Alexey Gotsman, Adam Morrison, Hongseok Yang, Marek Zawirski: Specification and Complexity of Collaborative Text Editing.

**PODC 2016** 

#### Wrap Up

Systematic study of replicated data stores

- Tighten consistency result, message size & metadata bounds
- Explore assumptions (push-based): remove them or get better algorithms by violating them
- Incorporate garbage collection
- Go beyond plain text editing, e.g., spreadsheets and other objects