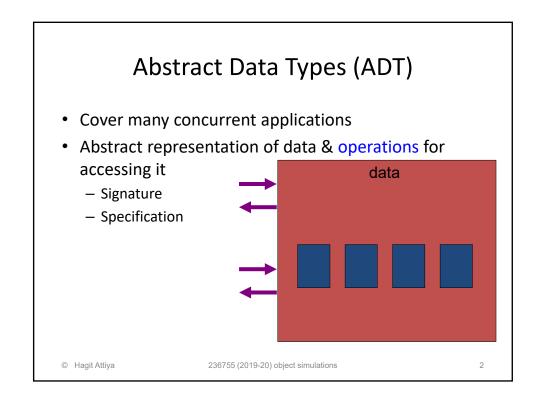
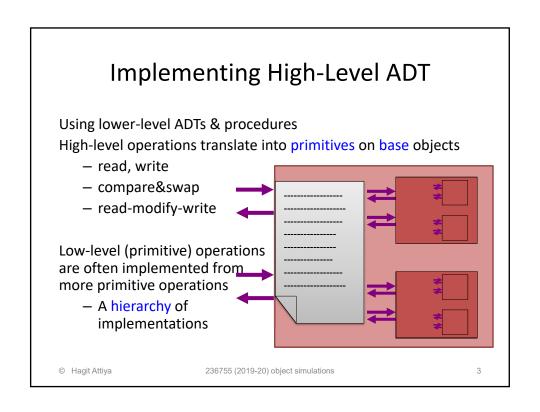
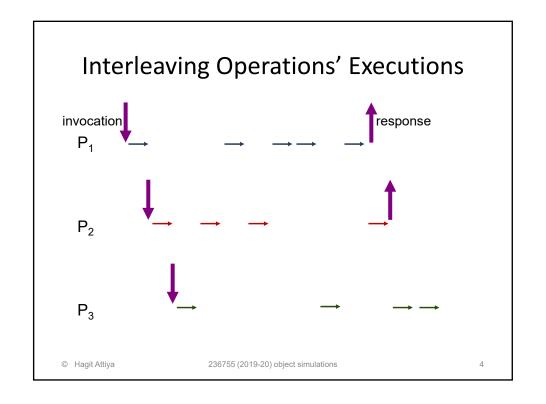
236755 Topic 4: Simulating Shared Objects

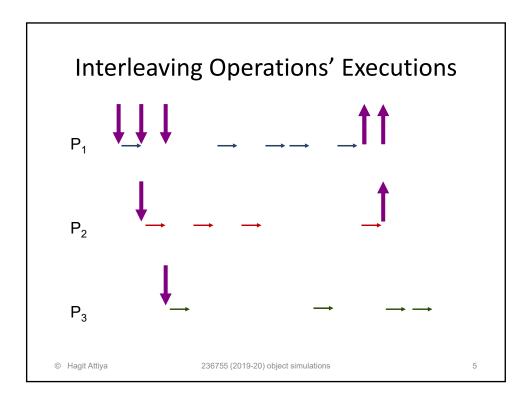
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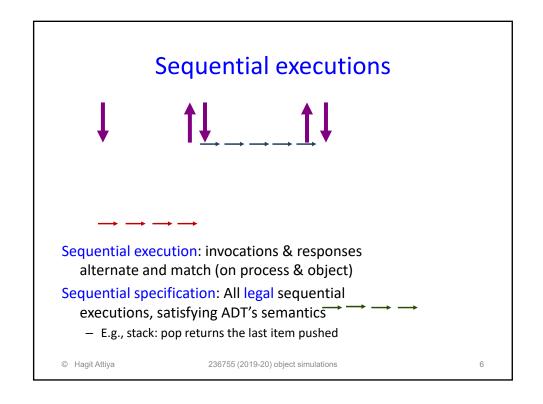
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Correctness: Linearizability

- For every concurrent execution, there is a sequential execution of the same operations that
 - Is legal (obeys the specification of the ADTs), and
 - Preserves the real-time order of non-overlapping operations
- Equivalently, each operation appears to takes effect instantaneously at some point between its invocation and its response (atomicity)
- When processes fail (there is a partitioning of processes into faulty and nonfaulty), this holds for all completed operations and a subset of the pending operations

Some operations never complete

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Linearizability is Composable (Local)

- The whole system is linearizable
 ⇔ each object is linearizable
- Allows to implement and verify objects separately

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General Objects

Registers support *read* and *write* operations Later, we'll see wait-free simulations of one kind of register out of another kind (# values, readers, writers)

What about (wait-free) simulating a significantly different kind of data type out of registers?

More generally, what about (wait-free) simulating an object of type *X* out of objects of type *Y* ?

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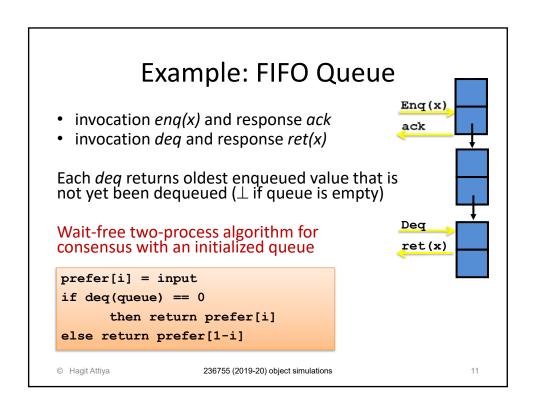
Key Insight

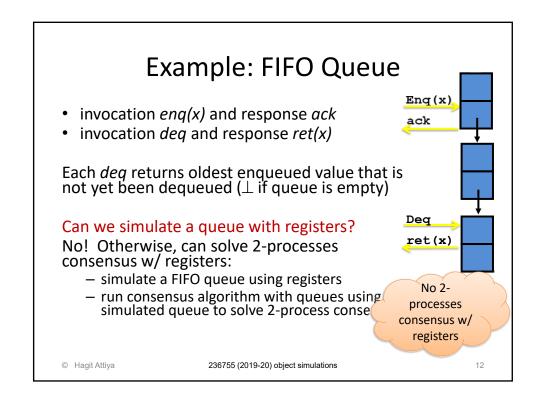
- Focus on asynchronous, wait-free simulations
 - Typically, in shared memory

Ability to simulate object of type X using only objects of type Y and registers is related to the ability of those data types to solve consensus (or other problems)

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Example: k-Sliding Window Register

Sequence of values accessed with two operations: **k-write**(*v*) adds v at the end of the sequence **k-read**() returns an ordered sequence of the last k values written (pad if < *k* values have been written)

Boils down to an ordinary register, when k = 1

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Example: k-Sliding Window Register

Sequence of values accessed with two operations: **k-write**(*v*) adds v at the end of the sequence **k-read**() returns an ordered sequence of the last k values written (pad if < *k* values have been written) Can solve consensus among *k* processes

```
\begin{aligned} & propose\left(v_{i}\right) \\ & k\text{-register.write}\left(v_{i}\right) \\ & seq \; \leftarrow \; k\text{-register.read}() \\ & return \; \text{first non-1} \; value \; \text{in seq} \end{aligned}
```

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Example: k-Sliding Window Register

Sequence of values accessed with two operations: **k-write**(*v*) adds v at the end of the sequence **k-read**() returns an ordered sequence of the last k values written (pad if < *k* values have been written) Can solve consensus among *k* processes

Cannot solve consensus among *k+1* processes Standard bivalence-style proof (similar to queue)

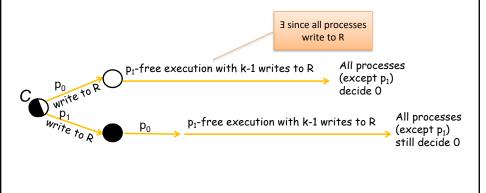
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Core Case of the Proof

Critical configuration, where the next steps by all k+1 processes are writes to the same window register R



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Consensus Numbers

Data type X has **consensus number** CN(X) = n if n is the largest number of processes for which consensus can be solved using only objects of type X and read/write registers

Determine if there is a wait-free simulation of Y from X based on their consensus number

data type	consensus number
read/write register, snapshots	1
FIFO queue, fetch&Inc	2
<i>k</i> -window register	k
compare &swap	∞

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Consensus Numbers

Data type X has **consensus** number CN(X) = n if n is the largest number of processes for which consensus can be solved using only objects of type X and read/write registers

data type	consensus number
read/write register, snapshots	1
FIFO queue, fetch&Inc	2
<i>k</i> -window register	k

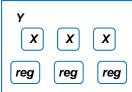
Theorem: If n = CN(Y) > CN(X) = m, then there is no wait-free simulation of an object of type Y using objects of type X and read/write registers for > m processes

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Consensus Numbers: Proof

Assume there is a wait-free simulation of Y using X and registers in a system with k, $n \ge k > m$ processes



Consensus algorithm for *k* processes

- Since CN(Y) = n, there is a k-process consensus algorithm using Y and registers
- Execute this algorithm using simulated objects of type Y from objects of type X (and registers)

Theorem: If n = CN(Y) > CN(X) = m, then there is no wait-free simulation of an object of type Y using objects of type X and read/write registers for > m processes

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Sample Corollaries

There is no wait-free simulation of any object with consensus number > 1 using read/write registers

There is no wait-free simulation of any object with consensus number > 2 using queues and read/write registers

There is no wait-free simulation of any object with consensus number > k using k-window registers

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Universality of Consensus Numbers

Data type is **universal** if objects of that type and read / write registers can wait-free simulate any data type

Theorem: A data type with consensus number n is universal for a system with $\leq n$ processes

- A non-blocking n-process algorithm to simulate any data type using compare & swap
- 2. Modify to use objects with consensus number n
- 3. Modify to be wait-free
- 4. Bound the shared memory used and handle nondeterminism

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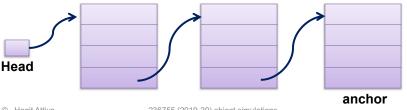
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Universal Simulation Using CAS

Represent object by a linked list with the sequence of operations applied to the simulated object

Apply an operation on the simulated object by inserting an appropriate node at the head of the linked list Use compare&swap on the Head pointer of the list



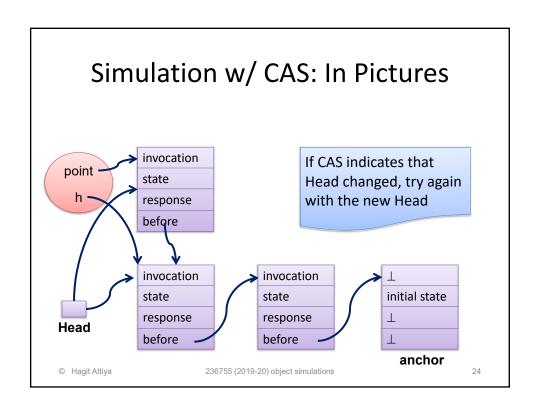
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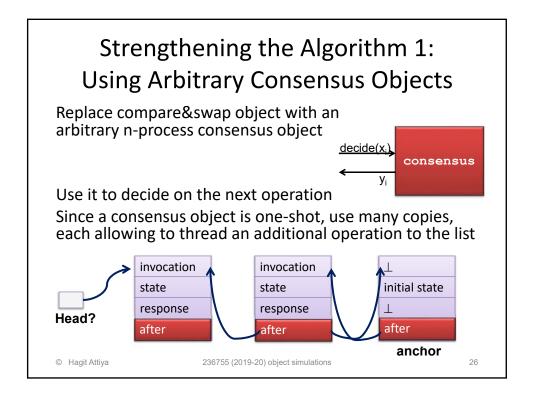
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The Linked List Each linked list node has operation invocation (= type and parameters) new state of the simulated object • operation response • pointer to previous node (= previous op) invocation invocation initial state state state response response Head before before \perp anchor © Hagit Attiya 23 236755 (2019-20) object simulations

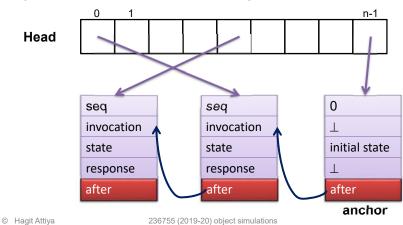


Simulation w/ CAS: The Code Initially Head points to anchor node represents initial state of simulated object local variables h, point When inv is invoked: allocate a new linked list node in shared memory, pointed to by local var point point.inv = inv repeat depends on simulated data type h = Headpoint.state, point.response = apply(inv,h.state) point.before = h Head not changed, until compare&swap (Head, h, point) == h point it to new node do the output indicated by point.response 236755 (2019-20) object simulations



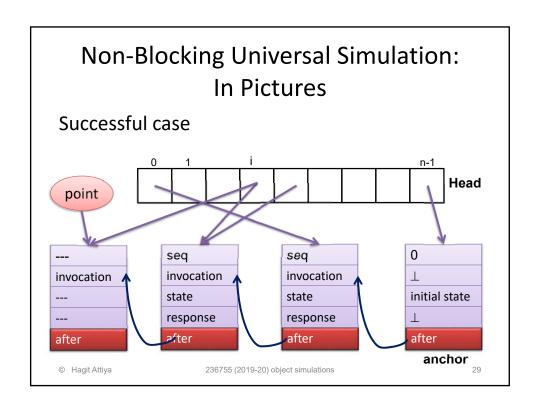
Strengthening the Algorithm 1: Finding the Head of the List

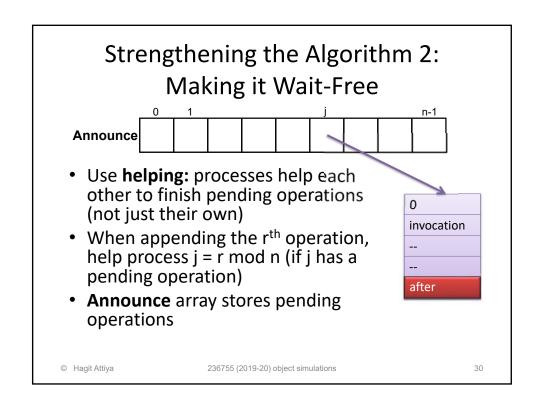
Per-process Head pointer, to the last node it has inserted Sequence numbers allow to identify the latest node



Algorithm with Consensus Objects

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Code for Wait-Free Simulation

```
Initially all Head and Announce entries point to anchor
When inv occurs
  Announce[i] = new opr, Announce[i].inv,seq = inv,0
  for j=0 to n-1
       if Head[j].seq > Head[i].seq then Head[i]=Head[j]
  while Announce[i].seq == 0 do
       priority = Head[i].seq+1 mod n
                                                   process with priority
       if Announce[priority].seq == 0 then
                                                   help is needed
              point = Announce[priority]
                                                   help the other process
       else point = Announce[i]
                                                   perform own operation
       win = decide(Head[i].after, point)
                                                   like before
       win.state,reponse = apply(win.inv,Head[i].state)
       win.seq = Head[i].seq+1
       Head[i] = win
  return Announce[i].response
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```

Strengthening the Algorithm 3: Bounding the List

A process allocates nodes from a private pool

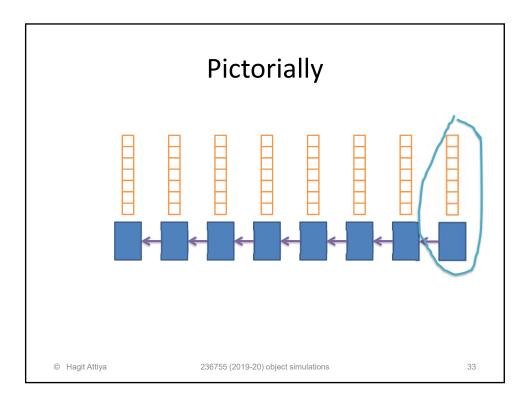
A node is recycled when it is not referenced anymore

When can we recycle node #r?

- No process trying to thread node ≥ (r+n+1) will access node r
- When the operations that thread nodes r...r+n terminate, node r can be recycled
- When a process p finishes threading node m it releases nodes m-1...m-n.
- After node r is released by the operations threading nodes r...r+n, it can be recycled

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Strengthening the Algorithm 3: Randomized Consensus

- Suppose we relax the liveness condition for linearizable shared memory:
 - operations must terminate with high probability
- Now a randomized consensus algorithm can be used to simulate any data type out of any other data type, including read/write registers
- Need to have a non-deterministic simulation since different processes will have different outcomes

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Simulating Read / Write Objects

Can we provide a **shared read / write variable** in an asynchronous message-passing system, when processes can fail?

• Yes, if we have enough nonfaulty processes

Can we provide **stronger types** of read / write variables, when processes can fail?

Yes, as long as we don't read-and-write

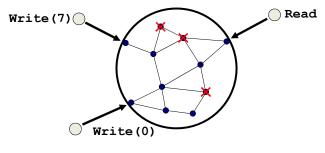
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Simulating Shared Memory

- Provide a single-writer single-reader register (this is the highlevel) in a message-passing system
 - Accessed by read and write operations
- Underlying system is asynchronous message passing (this is the low-level), where less than half the processes can crash

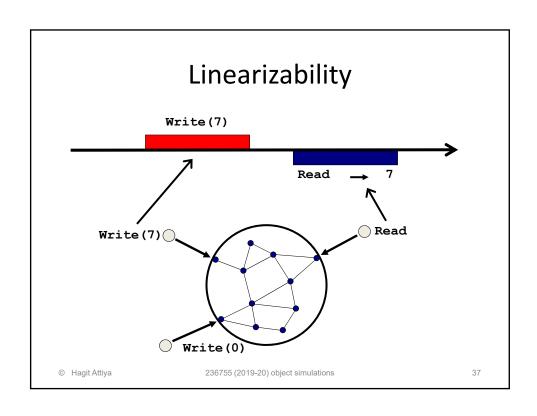


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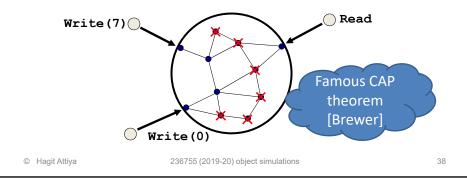
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Simulating Shared Memory w/ Failures

- Requires a majority of nonfaulty processes
- Otherwise, the system can be partitioned
 - A read "misses" the latest write

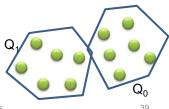


Must have n > 2f

Theorem: A simulation of a 1-reader, 1-writer read/write linearizable register in an asynchronous message passing tolerates at most f < n/2 crash failures

Proof: Suppose in contradiction there is an algorithm tolerating f = n/2 crash failures

Partition processes into two sets, Q_0 and Q_1 , each of size f



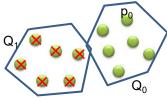
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Must have n > 2f: Writing

Consider an execution in which

- initial value of simulated register is 0
- all processes in Q₁ crash initially
- process p_0 in Q_0 invokes write(1) at time 0 and no other operations are invoked
- the write completes at some time t_0 without any process in Q_0 receiving a message from any process in Q_1



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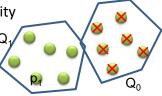
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Must have n > 2f: Reading

Consider another execution in which

- initial value of simulated register is 0
- all processes in Q_0 crash initially
- process p_1 in Q_1 invokes a read at time t_0 +1 and no other operations are invoked
- the read completes at some time t_1 without any process in Q_1 receiving a message from any process in Q_0

- the read returns 0, due to linearizability



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Must have n > 2f: Arithmetic

Now paste the views of processes in ${\bf Q}_0$ from the first execution with the views of processes in ${\bf Q}_1$ from the second execution

– messages between Q_0 and Q_1 are delayed to arrive after time t_1

This execution is not linearizable, since read(0) follows write(1)

→ Must assume a majority of nonfaulty processes

Q₁ Q₀

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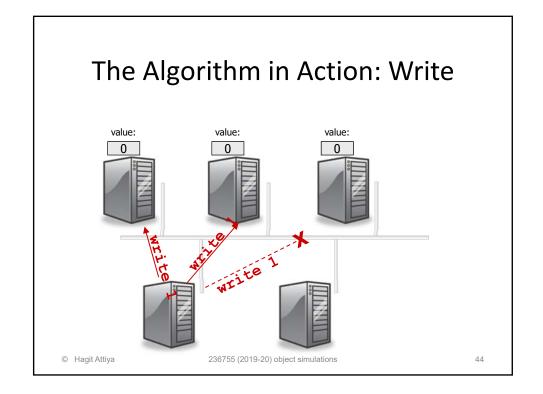
The Algorithm in a Nutshell: Write

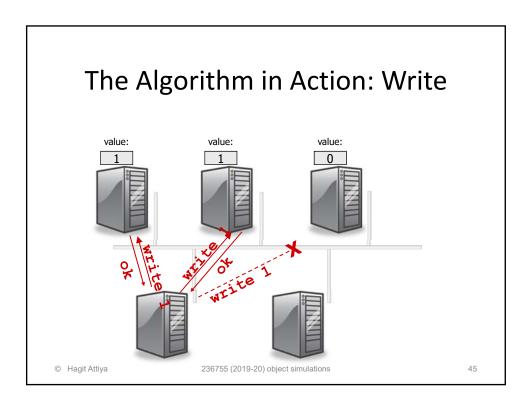
- The simulated register is replicated at each process
- Each data item has a unique sequence number
 - sequence of values
- write(d, val, seq#)
 - generate next sequence number
 - send a message with the value and the sequence number to all processes
 - each recipient updates its replica and sends ack
 - writer waits for n-f > n/2 acks

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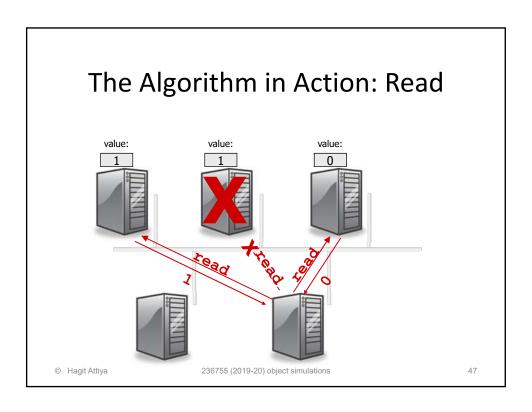


The Algorithm in a Nutshell: Read

- Each data item has a unique sequence number
- read(d) returns (val, seq#)
 - send a request to all processes
 - each recipient sends back current value of its replica
 - wait for > n/2 replies
 - return value associated with largest sequence number
 - do a write-back to ensure atomicity of reads

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Key Idea for Correctness

- Each read should return the value of "the most recent" write
- Each read or write communicates with > n/2 processes

→ The set of processes communicating with a read intersects the set of processes communicating with a write

- Since system is asynchronous, a message on behalf of an operation might be overtaken by a message on behalf of a later operation
 - reader and writer keep track of "status" of each link
 - don't send a message on a link before receiving ack on previous message (ping-pong)

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Proving Linearizability

Let ts(W) = sequence number of WLet ts(R) = sequence number of write that R reads from $O_1 \rightarrow O_2$ denotes O_1 completes before O_2 starts

Key lemmas:

- If $W_1 \rightarrow W_2$, then $ts(W_1) < ts(W_2)$ one writer generates ts
- If $W \rightarrow R$, then $ts(W) \le ts(R)$
- If $R \to W$, then ts(R) < ts(W)
- If $R_1 \rightarrow R_2$, then $ts(R_1) \le ts(R_2)$

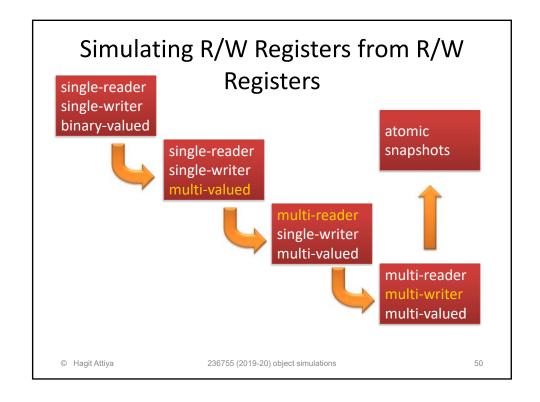
can't read from the future

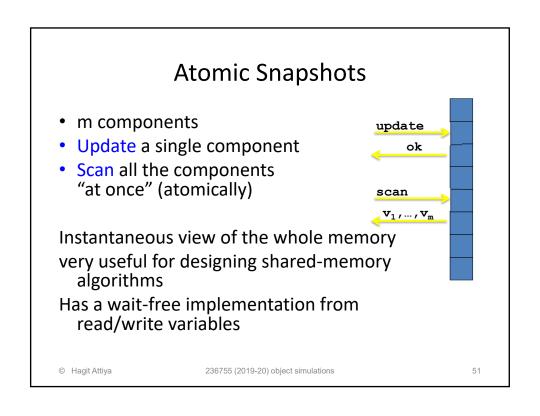
majorities intersect

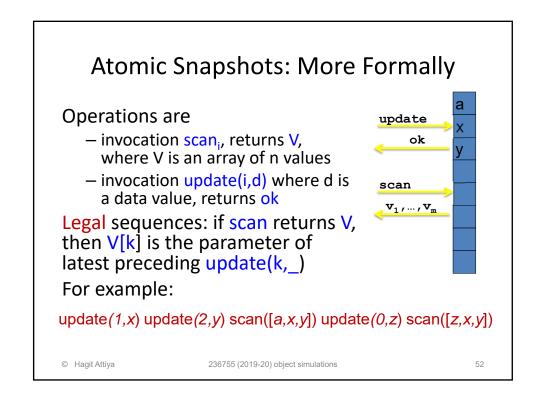
majorities intersect

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Atomic Snapshots: 1st Idea

- Store each component in a separate variable
- To update: write to the respective variable
- To scan: Collect (read) values of the segments twice
 - If no segment is updated during the "double collect"
 ⇒ this is a valid snapshot ⇒ return it
- How to tell if a segment is updated?
 - Tag each value with a sequence number (1,2,3,...)

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Atomic Snapshots: Partial Algorithm

```
\label{eq:double_collect} \begin{array}{ll} \text{Update}\,(k\,,v) & \text{Scan}\,() & \text{double collect} \\ A[k] = \langle v\,, \text{seq}_i\,, i \rangle & \text{repeat} & \\ & \text{read A[1]}\,,...,A[m] \\ & \text{read A[1]}\,,...,A[m] \\ & \text{if equal} & \\ & \text{Linearize:} \\ \bullet \text{ Updates with their writes} \\ \bullet \text{ Scans inside the double collects} & \\ \end{array}
```

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Atomic Snapshot: Linearizability

Double collect (read a set of values twice)

If equal, there is no write between the collects

— Assuming each write has a new value (seq#)

Creates a safe zone, where the scan is linearized

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Wait-free Atomic Snapshot

Embed a scan within the update & write its view to the segment Scanner returns view obtained in last collect

```
Update(v,k)
                               Scan()
                                                       direct
                                                        scan
V = scan
                               repeat
A[k] = \langle v, seq_i, i, V \rangle
                                  read A[1],...,,A[m]
                                  read A[1], ..., A[m]
                                  if equal
                                     return A[1,...,m]
Linearize:
                                  else record diff

    Updates with their writes

                                  if twice pi
· Direct scans as before
                                                     borrowed
· Borrowed scans with source
                                                       scan
                                    return V.
```

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Atomic Snapshot: Borrowed Scans

Interference by process p_j
And another one...

⇒ p_i does a scan inbeteween



Linearizing with the borrowed scan is OK.

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Complexity of Atomic Snapshots

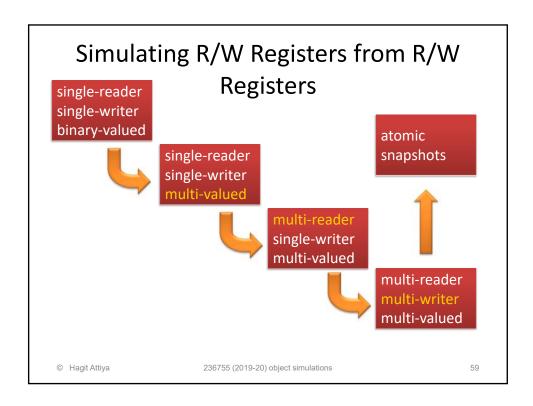
Uses O(m) read/write variables (some are large)

Scan needs $O(n^2)$ reads and writes, why?

Update needs $O(n^2)$ reads and writes

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Multi-Writer from Single-Writer: Key Ideas

- Each writer announces each value it wants to write to all the readers, by writing the value to its own (single-writer multi-reader) register
- Each reader reads all the values written by the writers and returns the latest one
- How to determine latest value?
 - use timestamps (as in Bakery algorithm)
 - since multiple processes generate timestamps, need to coordinate timestamp generation

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Multi-Writer from Single-Writer

✓ Wait-free by construction

Create linearization:

- Place writes in timestamp order
- Insert each read before the write following the write it returns

Add logical time to values

```
Write (v, X)

read TS_1, \dots, read TS_n

TS_i = max TS_j + 1

write \langle v, Ts_i, i \rangle to R_i
```

```
Read(X)
read R<sub>1</sub>,...,read R<sub>n</sub>
return v<sub>j</sub> with
  maximal <TS<sub>j</sub>,j>
```

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Multi-Writer from Single-Writer

✓ Wait-free by construction

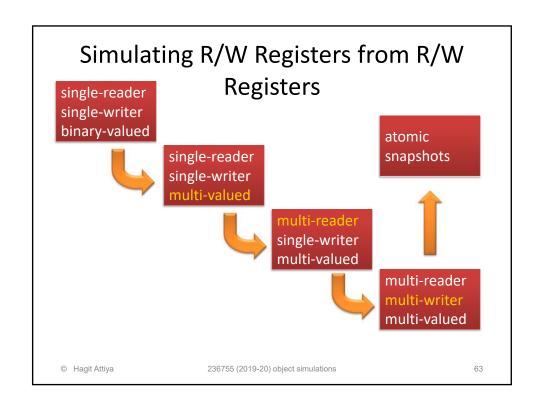
Create linearization:

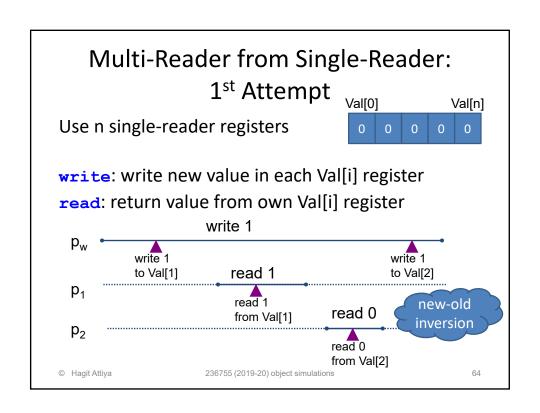
- Place writes in timestamp order
- Insert each read before the write following the write it returns
- ✓ Legality is immediate
- ✓ Real-time order is preserved since a read returns a value (with timestamp) larger than all preceding operations

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Readers Must Write

Theorem: In a wait-free simulation of a multi-reader single-writer register from single-reader single-writer registers, at least one reader writes

Proof: Suppose, in contradiction, there is an algorithm in which readers never write

- $-p_w$ is the writer, p_1 and p_2 are the readers
- initial value of simulated register is 0
- $-S_1$ are the single-reader registers read by p_1
- $-S_2$ are the single-reader registers read by p_2

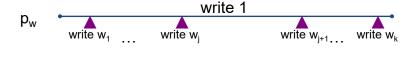
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Readers Must Write

- Consider execution in which p_w writes 1 to the simulated register, by a sequence of writes, $w_1,...,w_k$, to the single-reader registers
 - Each of them is either in S_1 or in S_2 (but not both)



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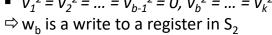
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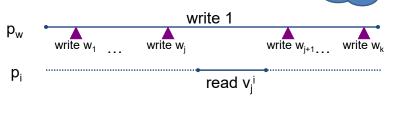
66

Readers Must Write

 v_j^i denotes the value returned if p_i reads after w_j For each reader p_i the value of the simulated register "switches" from 0 (old) to 1 (new), at some point

- $v_1^1 = ... = v_{a-1}^1 = 0$, $v_a^1 = ... = v_k^1 = 1$ ⇒ w_a is a write to a register in S_1
- $v_1^2 = v_2^2 = \dots = v_{b-1}^2 = 0, v_b^2 = \dots = v_k^2 = 1$





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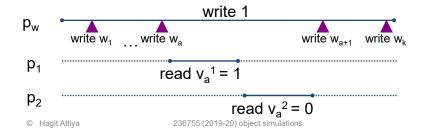
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Readers Must Write

Assume a < b

Since readers do not write, they return the same values as when running alone

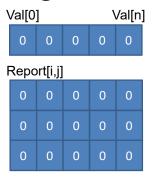
⇒ new-old inversion, not linearizable





In the simulated read, announce the value to be returned

Check values returned by previous reads



Sequence numbers allow to compare returned values

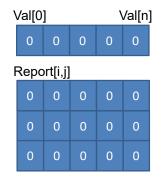
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Writer's Algorithm

- get the next sequence#
 - an integer, incremented by 1 each time
- write (value, sequence#)
 to Val[1],...,Val[n]
 (one copy for each reader)



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Reader p_i 's Algorithm

Val[0]

Report[i,j]

- read (value, sequence#) from Val[i]
- read (value, sequence#) from Report[j,i]
- pick pair with largest sequence#
- write that pair to row i of Report
- return value component of that pair

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Val[n]

Correctness of Multi-Reader Algorithm

- · Obviously wait-free
 - Write: *n* primitive writes
 - Read: n+1 primitive reads and n primitive writes
- To prove linearizability, show a permutation of the high-level operations that is clearly legal and then prove it preserves real-time order of non-overlapping operations

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Constructing the Permutation

- Put all writes in the order they occur in the execution
 - Single writer ⇒ writes do not overlap
- Consider the reads in the order of their responses in the execution
 - read R reads from write W if W generates the sequence# associated with the value R returns
 - place R immediately before the write that follows W
- By construction, the permutation is legal

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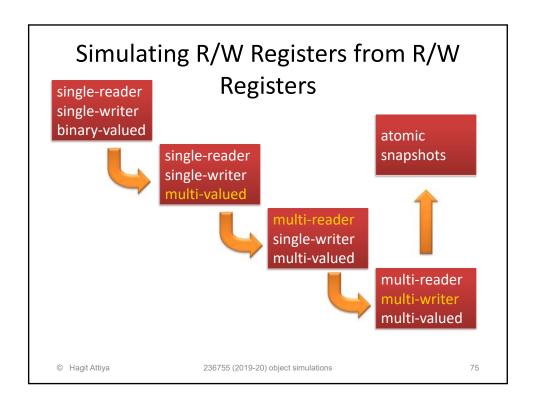
Preserving Real-Time Order

- write-write: by construction
- read-write: R precedes W in the execution.
 Then R cannot read from W or any later write.
 ⇒ R is placed before W in the permutation
- write-read: W precedes R in the execution.
 Then R reads W's sequence# or a larger one from Val[] and reads from W or a later write.
 - \Rightarrow R is placed after W in the permutation
- read-read: R_i by p_i precedes R_j by p_j in the execution.
 Then p_j reads R_i's sequence# or a larger one from Report[i,j].
 - \Rightarrow R_i reads from the write that R_i read from or a later one
 - $\Rightarrow R_i$ is placed after R_i in the permutation

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Multi-Valued From Binary

The simulated register takes values {0,...,K-1}

Binary approach: a different binary register stores each bit of the multi-valued register being simulated

- Read algorithm reads all registers and returns the resulting value
- Write algorithm writes the new bits in some order

Errors when the reader overlaps a slow write and sees some new bits and some old bits

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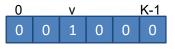
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A Unary Approach

Use an array of K binary registers, B[0..K-1]

- value v is represented with B[v] = 1 and other entries 0
- Read algorithm: read *B*[*0*], *B*[*1*],..., until finding the first 1; return the index
- Write algorithm: set new entry of B and zero the old entry of B

OK if reads and writes don't overlap.



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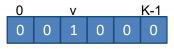
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When Reads and Writes Overlap...

Problem: reader may never find a 1 in B

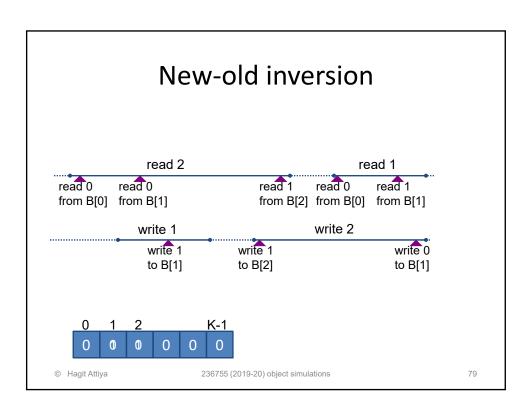
Solution: write algorithm only clears (sets to 0) entries

that are smaller than the entry that is set (to 1)



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Corrected Algorithm

Read: scans up to first 1, then read down to check those entries are still 0; return smallest index set during downward read

Write(r): set r to 1 and then set to 0 entries smaller than r

Clearly, wait-free:

- writer does at most K (primitive) writes
- reader does at most 2K-1 (primitive) reads



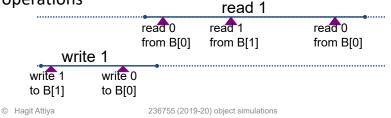
Linearization Proof for Multi-Valued Construction

Fix an admissible execution of the algorithm

- Primitive operations (binary read / write) are atomic

We give a permutation of the (high-level) operations that is legal (by construction)

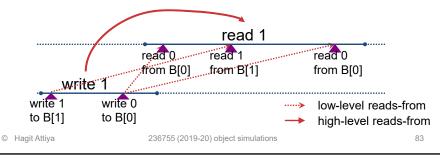
Show it respects real-time ordering of non-overlapping operations



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Reads-From Relations

Primitive read r of a binary register B[v] reads from primitive write w to B[v] if w is the latest write to B[v] that precedes r in the execution High-level read R reads from high-level write W if R returns v and W contains the primitive write that R's last primitive read of B[v] reads from



The Permutation

Primitive read r of a binary register B[v] reads from primitive write w to B[v] if w is the latest write to B[v] that precedes r in the execution High-level read R reads from high-level write W if R returns v and W contains the primitive write that R's last primitive read of B[v] reads from

- Place (high-level) writes in the order they occur
 - no concurrent writes
- · Consider each (high-level) read R in the order they occur
 - no concurrent reads
- If R reads from write W, place R immediately before the write that follows W in the permutation

 Legal by

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construction

Permutation Preserves Real-Time Order

- write-write: OK, by construction
- read-write: OK, since cannot read from a later write
- Two cases remain:
 - write-read
 - read-read

Lemma: Assume a high-level read R returns v, and R read of any B[u], u < v, during its upward scan, reads from a primitive write contained in high-level write W. Then R does not read from a write that precedes W.

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